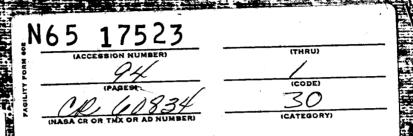
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FINAL REPORT -

ADVANCED MISSION
ANALYSIS STUDY

For:

Jet Propulsion Laboratory Pasadena, California

LOCKHEED . CALIFORNIA COMPANY A DIVISION OF LOCKHEED AIRCRAFT CORPORATION

SPACECRAFT ORGANIZATION

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1.0 SUMMARY

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This report is a summary of the results of a study devoted to the development of a quantitative method of comparing advanced space missions for the 1970 to 1990 time period. Five advanced missions were considered and the relationships of cost, reliability, schedule and system performance were investigated.

The missions considered were:

- 1. Unmanned Fly-by with Entry Probe to Jupiter
- 2. Manned Lunar Base
- 3. Earth Orbiting Manned Space Station
- 4. Manned Mars Landing and Return
- 5. Unmanned Sample Return from Venus.

Although Mission One - Jupiter Probe is used to illustrate the methods developed, summary results for the other missions are included. These results include identification of long lead time development items, system description and performance required, and a summary of the mission evaluation criteria.

In general, a system performance index has been developed for selecting the best system candidate within a particular mission; this system performance index is a space oriented cost effectiveness. In addition, a Mission Evaluation Criterion has been developed, and applied to five advanced space missions. This Mission Evaluation Criterion is a decision making tool to choose among space missions; it is useful in exploratory and screening mission studies as well as in evaluating missions whose technical feasibility and cost have already been established by studies in great depth.

author

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2.0 INTRODUCTION

As the progress of the national space program accelerates there is an ever growing list of technically possible future space missions to examine. What are the criteria to be used by decision makers in selecting the next manned and unmanned space missions? This study is devoted to answering this key question.

In other words, the purpose of this study is to develop a quantitative method of comparing advanced space missions for the 1970 - 1990 time period. Five advanced missions will be considered in the development of the method; and the relationships of cost, reliability, schedule, and system performance will be investigated and shown.

The scope of this undertaking is quite ambitious - involving both tangible technical analysis and intangible value judgments. The method of comparing space missions will be developed in such a way as to allow the value judgments to be made by JPL/NASA; thus the bias of individuals and the contractor will be eliminated.

In addition, a system performance index will be developed for comparing system candidates for a particular mission; and a mission evaluation criterion is developed for comparing missions.

This study is performed in support of Jet Propulsion Laboratory and in accordance with the terms and conditions of JPL Contract No. 950579.

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3.0 MISSION OBJECTIVES - GENERAL

In order to develop the method five advanced space missions were considered. These missions and their appropriate premises are tabulated below:

Premises for Mission One - Jupiter Probe

Time Period for Mission Accomplishment - 1970 to 1975.

Mission Duration - Two to four years.

Unmanned

Mission Objectives - Particle and field measurements; pictures at closest approach; entry capsule to measure primary atmospheric variables, minimum atmospheric composition and establish an unmanned station.

Premises for Mission Two - Manned Lunar Base

Time Period for Mission Accomplishment - 1972 to 1980.

Mission Duration - One Year.

Crew number for resupply vehicles - 3 minimum.

Passenger number for resupply vehicles - as required.

Mission Objectives - Establish a lunar base and perform the logistics resupply mission with primary emphasis on the logistics resupply capability. The base is manned to perform lunar exploration, observation of earth, astronomy mapping and similar operations.

Premises for Mission Three - Earth Orbiting Manned Space Station

Time Period for Mission Accomplishment - 1970 to 1975.

Mission Duration - 1 Year.

Crew Number - 6 to 30 men.

Mission Objectives - Establish low earth orbiting space station with resupply capability. The station would be used as an orbital research laboratory for experiments and observations or support for orbital assembly and launch of lunar and interplanetary vehicles. Primary emphasis will be placed on a station for assembly, check-out and launch of interplanetary vehicles.

Premises for Mission Four - Manned Mars Landing and Return

Time Period for Mission Accomplishment - 1977 to 2000.

Mission Duration - Up to two years.

Crew Number - 6 to 12.

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Mission Objectives - Planetary observations, two week stay time, limited exploration and return of samples not to exceed 50 (earth) pounds.

Premises for Mission Five - Unmanned Sample Return from Venus

Time Period for Mission Accomplishment - 1970 to 1980.

Mission Duration - One to two years.

Mission Objectives - Entry and soft landing on the surface of the planet and return of a minimum of one (earth) pound of material from the planet to earth.

The reason for selecting these missions are:

- 1. both manned and unmanned missions are considered;
- 2. these missions are reasonably representative samples for the development of a method of comparing missions where the relationships of cost, reliability and system performance index are considered.

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4.0 STUDY PROCEDURE

In order to show the study procedure and the relationship of various technical activities, Figure 1 is presented.

The procedure begins with Item 1, Missions Definition and is completed with Item 3, Mission Evaluation. Item 2, Operational Modes, includes trajectory selection and determination of the velocities required for various mission profiles, trip times and launch dates.

Item 3 is the synthesis of system candidates on the basis of available subsystem technology. For example, fast nuclear reactors might be considered after 1975, and similarly large launch vehicles utilizing clustered solid rockets might be considered after 1966.

Concurrent consideration of Item (4), Operations Analysis and Item (5), Vehicle Design and Analysis will lead to Item (6) the Definition of System Candidates that are feasible from the standpoint of flight performance and other technical considerations. Item (7) is the evaluation of feasible system candidates that have been defined and described in Item (6).

Moreover, in Item (), the system performance index is used to select the best system candidate within any one mission. Thus, System Performance Index is a system evaluation criterion; it is defined and explained in greater detail in Section 5.6. In addition, under Item (), the programming variations shown relate to number of launches, launch date, trip time, and type of development schedule; further details are given in Section 5.6.4.

In Item (3), Mission Evaluation, a mission evaluation criterion is considered as well as the intangible value judgments required to show the relative value of each mission. These judgments will be performed at the policy level at JPL/NASA and not by the contractor. Similarly, the incremental mission return factors for the System Performance Index represent value judgments that will be provided by JPL/NASA.

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5.0 MISSION ONE - JUPITER PROBE

In order to illustrate the methods developed, Mission One - Jupiter Probe will be discussed, in detail now, and summary results for the other missions will be shown in Section 6.0.

5.1 Operational Modes

In general an operational mode describes the flight path, communications links, and all techniques for flight and surface operations that are required to accomplish the science and engineering objectives of a mission. In this study the selection of operational modes is limited to reasonable projections of the current technology to the time period for mission accomplishment.

The operational modes that were initially selected for consideration are summarized on page 8 and illustrated in the appendix,

Operational Mode 3a (Figure 2) was selected to demonstrate the evaluation techniques being developed in this study. This mode entails the launching of a space-craft to penetrate transjovian space and to explore the atmosphere of the planet and the adjacent region. Data from scientific measurements made enroute to the vicinity of Jupiter will be telemetered directly to a terrestrial station. On arriving at the target planet the orbiter/entry capsule is released for planet capture; subsequently the measurements are made by instruments aboard both the main spacecraft and the capsule. Data collected by the capsule is telemetered to the main spacecraft from which it is then transmitted earthward. Capsule-to-spacecraft and spacecraft-to-earth data transmission will not be possible at all times; therefore, data storage capability must be provided on board both vehicles.

Estimated velocity requirements for three different interplanetary trip times for the Jupiter Probe mission are shown in Table I. Evaluations of the mission were made for all three trip times shown. The velocity requirements were estimated by means of References 4, 6 and a graphical method developed in support of this study. Details of the graphical technique are presented in the appendix of this report.

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5.1 Operational Modes

- 1. <u>Flyby</u> Spacecraft is launched into earth orbit, from which it is injected on an interplanetary trajectory which penetrates the near vicinity of Jupiter. (Figures 1 and 7).
- 2. Main Spacecraft in Capture Orbit Spacecraft is launched into earth orbit, from which it is injected on a trans-Jovian trajectory. Retrograde velocity adjustments applied near the perijove of the trajectory establishes the spacecraft in an elliptical orbit around the planet. (Figures 2 and 7).
- 3. Flyby with Orbiter Capsule Release Spacecraft is launched into earth orbit and injected on flyby trajectory. Near the perijove of the hyperbolic flyby trajectory an instrumented capsule is released from the main spacecraft. Retrograde velocity adjustments enable the capsule to transfer to an elliptical capture orbit. Main spacecraft later provides a communications link between the orbiting capsule and terrestrial stations. (Figures 3 and 7).
 - 3a. Flyby with Orbiter/Reentry Capsule Release Same as (3) above except that the altitude of the orbiting capsule is diminished periodically by transfer to smaller orbits. The capsule spirals incrementally toward the planet, eventually entering the jovian atmosphere. (Figures 3 and 7).
- 4. Flyoy with Orbiter Capsule Release and with Auxiliary Communications

 Spacecraft Same as (3) above except that a communications relay spacecraft
 is launched on an interplanetary trajectory to provide an additional
 communication link between the earth-returning main spacecraft and terrestrial
 monitoring stations. (Figures 4 and 7).
- Flyby with Orbiter Capsule Release and with Earth Orbiting Communications
 Relay Same as (3) above except that an earth orbiting space station is
 used as a communication link between the earth-returning main spacecraft
 and terrestrial monitoring stations. (Figures 5 and 7).
- 6. Earth Oroital Assembly/Flyby with Orbiter Capsule Release Same as (3) above except that earth orbit assembly techniques are employed to enable buildup of large chemical propellant spacecraft. (Figures 6 and 7).

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TRAJECTORY DATA JUPITER PROBE TABLE I

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Total Trip Time (days)	766	730	548
Velocity Increments - Transfer, Capture, Etc. (ft/sec x 10-3) Earth Orbit (100 N.M.) Departure	20.75	21.35	23.35
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Velocity Increments - Guidance Maneuvers (ft/sec xlo-3)	-3)		
Injection .	0.5	0.5	Ā. 5
Midcourse	0.5	6.5	0.5
First Approach	1.0	1.0	1.0
Final Approach	1.0	1.0	1.0
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5.2 System Candidates

For each operational mode described previously, one or more system candidates were specified for preliminary consideration. The various subsystems considered in these candidates are shown in Table 2. The system candidate considered for further detailed study was, S-5, as shown by the combination of subsystems outlined in Table 2 by heavy rectangles.

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SYSTEM CANDIDATES - JUPITER PROBE

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5.3 Operations Analysis

The evaluation of selected operational mode/system candidate combinations by which a mission is implemented entails the assignment of value, hereafter called incremental mission return, to the functional objectives of the mission. This was done by first identifying all possible objectives of the mission which, if successfully accomplished, provide incremental mission return in the sense that a contribution is made to the nation's space flight program. These mission objectives are not limited to those which can be accomplished by specific operational mode/system candidate combinations; the list may include objectives which cannot be accomplished by any of the combinations.

Having identified the sources of value within a mission, each is assigned an incremental mission return factor (am.r.) based on the prorationing of points according to the value of each mission objective. In this study a total of one-hundred points were distributed among the objectives of each mission. Figure 3 shows a tabulation of objectives and assigned incremental mission returns for the Jupiter Probe mission when carried out by operational mode 3a. This particular operational mode enables the accomplishment of all possible mission objectives; hence, the total of the assigned incremental mission returns is one-hundred points.

Appropriate analyses were also conducted to establish a sequence of functional objectives for the operational mode/system candidate combination selected for evaluation. A functional sequence is essentially a list of engineering and science events which must be accomplished to fulfill the specific mission objectives. The events are listed in the order in which they occur in a normal mission. The successful completion of a single event in the sequence is not necessarily contingent on the successful completion of all prior events although this is frequently the case. Figure 4 in Section 5.3 shows a functional sequence for the Jupiter Probe mission when carried out by operational mode 3a.

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5.4 Vehicle Design & Flight Performance Analysis

In evaluating operational mode 3a and the selected system candidate, S-5, for the Jupiter Probe mission the spacecraft and capsule payloads, were considered to be invariant with trip time. Under this constraint the major considerations were the variation in retro velocity required for target planet capture and the variation in earth-orbit departure velocity. Figure 5 shows the relationship between trip-time and these two requirements while Figure 6 shows the effect of their variations on capsule weight and main spacecraft weight at departure from earth orbit.

In Figure 7 the spacecraft weight is again shown, along with the launch vehicle, Saturn 5, capability. This figure shows that for trip times of 997 days and 730 days the performance of the Saturn 5 launch vehicle is satisfactory for launch and earth-departure. The weight of a spacecraft designed for a 548 day trip however, exceeds the capability of the Saturn 5.

Susbystem investigations were carried out during this portion of the study primarily to obtain weight data and assess technical feasibility. The weight data for the best operational mode/system candidate combination for Jupiter Probe is tabulated in Section 5.5, System Definition.

In addition, a typical in-board profile made during the design investigations is shown on page 20 for the nuclear electric powered Jupiter Probe.

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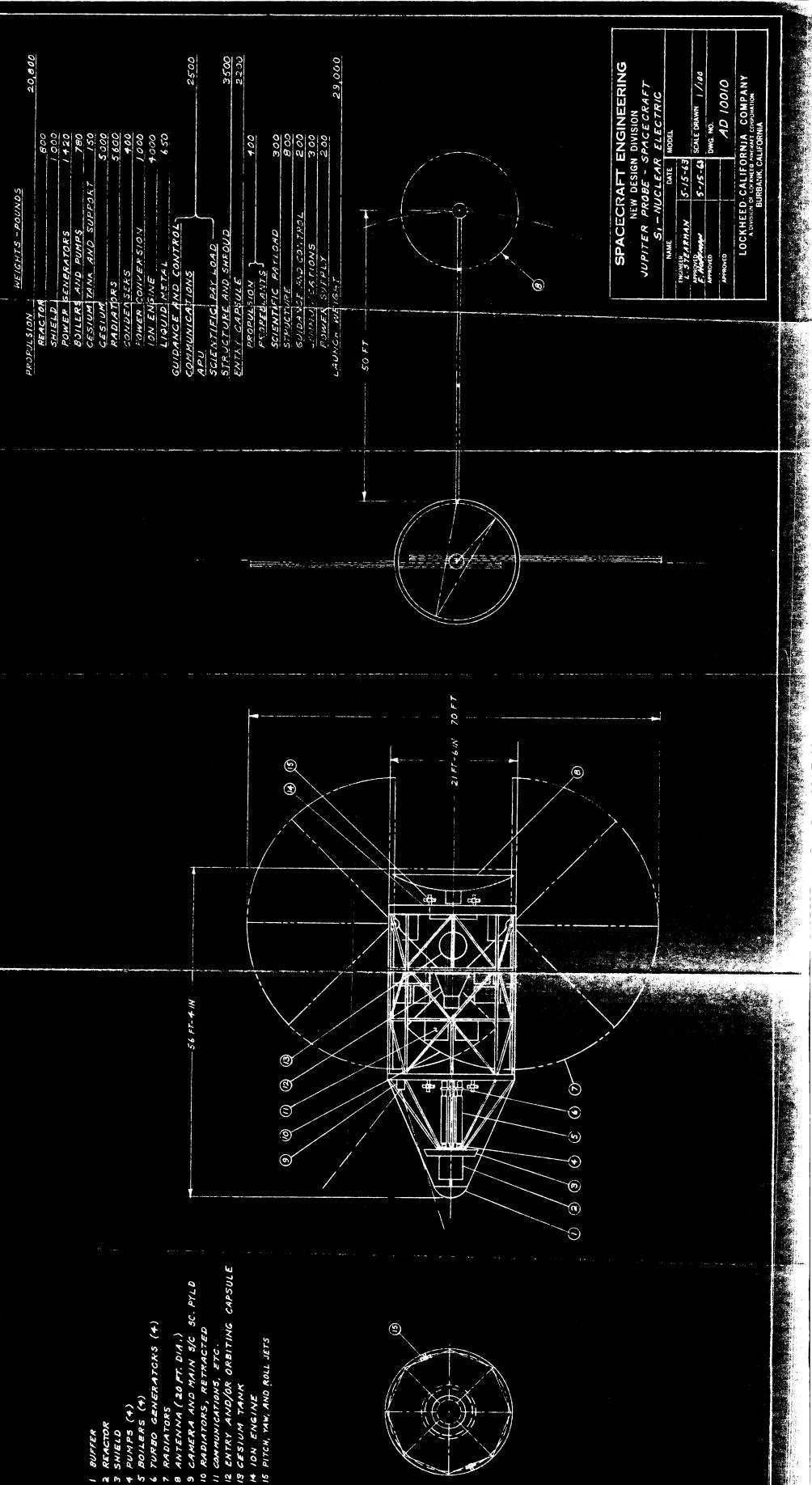
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5.5 System Definition

The system candidate selected for detailed evaluation in the Jupiter Probe mission is defined in this section.

Table 3 lists the major characteristics of the Jupiter Probe system candidate. This description together with the spacecraft weight summary in Table 4 represents the depth to which the system was defined for purposes of the evaluation. The results of analyses conducted in support of this definition appear in other sections of this report and in the appendix.

A Saturn 5 vehicle is used to launch the spacecraft into interplanetary trajectory via an earth parking orbit. Earth orbit is achieved after only a portion of the S IV B propellants are spent. Earth departure velocity is provided by the unspent propellants of the S IV B, thus requiring restart of that stage. The spacecraft provides only the propulsion required for mid-course correction guidance maneuvers during flight.

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TABLE 3 JUPITER PROBE SYSTEM CANDIDATE

MAIN SPACECRAFT

Payload - Scientific Equipment Guidance Propulsion - N₂O₁₄/Aerozine 50

Guidance - Astro - Inertial

Attitude Control - Reaction jets and inertia wheels

APU - Nuclear, 6 Kw

Communications - 2300 megacycles, 200 bits/sec.

CAPSULE

Payload - Scientific Equipment Planet Capture Propulsion - N_2O_4 /Aerozine 50

Deorbit Propulsion - N2O4/Aerozine 50

Power Supply - Battery
Guidance - Astro-Inertial :
Attitude Control - Reaction jets and inertia wheels
Communications

LAUNCH VEHICLE - SATURN 5

First Stage - S-IC Second Stage - S-II Third Stage - S-IV-B w/Restart

G.O.S.S. - Deep Space Instrumentation Facility

G.S.E - Saturn 5 and Spacecraft

LAUNCH FACILITY - Atlantic Missile Range.

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TABLE 4 SPACECRAFT WEIGHT SUMMARY

Spectrometers	70		
Magnetometers Radiation Detector	6.5		•
Radiometers	18.5 25		
Meteoroid Detector	5		
Television Camera Radio Noise Detector	5 25 5 45		
Controls, Scanners, Shields, etc.	45		
Environmental Control		620	
Reentry Capsule		4820	
Scientific Equipment	65		
Radiometers Meteoroid Detector	25 5		
Radiation Detector Magnetometers Controls, etc.	18.5 6.5 10.		
Communication System	60		
Environmental Control	35		
Guidance & Navigation Control	20 40		
Propulsion (Isp = 310)	3330		
Power Supply	110		
Structure and Reentry Shield	220		
Propulsion System (Isp = 310)		3700	
Engine Propellant Tanks	80 1 <i>6</i> 0		
Pressurization System	190		
Shielding and Insulation Structure	90		
Propellants	30 31 50		
Control		300	
Accessory Power Supply		800	
Communication System		480	
Suidance And Navigation		320	
Structure		700	

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5.6 System Evaluation

5.6.1 Reliability

The evaluation of a system candidate requires a quantitative determination of the candidate's capability to accomplish specified mission objectives. This is done on the basis of reliability analyses.

The first step in an evaluation procedure of this type is to identify the function or chain of sequential independent functions required to insure successful completion of mission objectives. Each objective to which incremental mission return factors (m.r.) have been assigned must be considered. The assignment of m.r.'s to mission objectives is covered in Section 5.3 of this report. Each of these functions is contingent on the proper operation of a set of subsystems. The reliability of the subsystems form the basis on which the probability of successfully accomplishing mission objectives is determined. Table 5 identifies the subsystems on which accomplishment of the various objectives of the Jupiter Probe mission depends.

The probability of successfully accomplishing mission objectives was first determined for a single mission attempt; that is, for a single launch program. The probabilities of accomplishing the various mission objectives in a single launch program were determined by:

$$R_{i} = \prod_{j=1}^{N_{i}} (R_{s})_{j} \prod_{k=1}^{N_{s}} e^{-\lambda_{k} t_{k}}$$

where:

R_i = Probability of successfully completing the ith mission objective.

(R_S) = Reliability of the jth "one-shot" or single-use subsystem required for accomplishing the ith objective

Total elapsed operating time required of the Kth continuoususe subsystem for accomplishing the ith objective.

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After determining the probability of successfully accomplishing each mission objective for a single launch program, the probability of successfully completing the objectives once in a multiple launch program can be determined by:

$$(R_1)_n = 1 - (1 - R_1)^n$$

where:

n = Number of launches in the program.

Table 6 presents the probabilities of accomplishing the Jupiter Probe mission objectives at least once for programs involving 1, 3, 6 and 9 launches as determined by the above method. In this summary table, the reliabilities of the individual science functions performed during a phase are not tabulated. The reliabilities shown in the table are effective reliabilities, computed by weighting the individual function reliabilities by the incremental mission return from each function.

The reliability data used in the Jupiter Probe evaluation is presented in Tables 7, 8, and 9. Figure 8: shows the launch vehicle reliability growth that can be expected during the Jupiter Probe program. No reliability growth was assumed in the determination of spacecraft function reliabilities.

Figure 9 shows a typical reliability estimate for a Jupiter Probe spacecraft subsystem and the equivalent subsystem for the Mariner spacecraft. It can be seen that an order of magnitude improvement in failure rate was assumed over that estimated for Mariner. The same magnitude of improvement was assumed over present capability for all Jupiter Probe subsystems.

TABLE 5

JUPITER PROBE

REQUIRED RELIABILITY CHAINS

MISSION OBJECTIVES

							17.	mox.	Jan J			,					
	oft	sction						JeAna		buver			C/	LPGUI	Œ		
S urs ys tens	Launch To Earth Orbit	Interplanetary Injection	Injection Maneuver	Phase I Science	Phase II Science	Midcourse Maneuver	Phase III Science	First Approach Maneuver	Phase IV Science	Final Approach Maneuver	Phase V Soience	Release	Capture	9e-orbit	Atmospheric Entry	Selence	
Leunch Vehicle	*****													· .			
Stages (3) Guidance 3rd Stage Restart	X X	X X X	X X	X X	X X X	X X X	X X X	X X	X X	X X X	X X X	X X X	X X X	XXX	X X X	X X X	
Spacecraft Engineering Guidance and Navigation Attitude Control Power Supply Communication Propulsion Capsule Release			X X X X	X X X X X	X X X	X X X X X	x x x x x x	x x x x x x 3	X X X X	X X X, X,	X X X X X X	X X X X X X	X X X, X, X, X	X X X X X	X X X X X X X X X X X X X X X X X X X	X X X X X X	÷ .
Capsule Engineering Guidance and Navigation Attitude Control Power Supply Communication Propulsion	٠.												X X X X	X X X	X X X X	X X X X	; ;
Spacecraft Science Spectrometers Magnetometers Radiation Detector Meteoroid Detectors Infrared Radiometer Microwave Radiometer Radio Noise Detector Television Camera				X	X		X X X		X X X		X X X X X						· 1.
Capsule Science Radiometer Meteorcid Detector Radiation Detector Magnetemeters Atmospheric Entry Sensors					•										x	X X X X	

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TABLE 6 PROBABILITY OF SUCCESSFUL OBJECTIVE ACCOMPLISHMENT

FUNCTION	TIME START	(Days) ELAPSED	11	PIANNED 3	IAUNCHES	9
Launch To Earth Orbit	0		.846	•996	•999	•999
Interplanetary Injection	0.5	~	•779	•989	•999	• 999
Injection Guidance Maneuver	1.5	-	•736	•982	• 999	• 999
Phase I Science	3	7	.746	-984	•999	•999
Phase II Science	10	79	•538	•902	• 994	•999
Midcourse Guidance Maneuver	88	-	.486	.854	.982	•998
Phase III Science	89	606	•044	.126	.234	•334
First Approach Maneuver	694	-	.047	.134	•251	•352
Phase IV Science	695	289	.011	.032	.062	.092
Final Approach Maneuver	900	-	.018	•055	.106	.1 55
Phase V Science - Spacecraft	984	17	.0089	•026	.057	.077
Capsule Separation	985	-	.017	.052	.101	.147
Capsule Planetary Capture	985	-	.0116	.004	.008	.0 1 2
Phase V - Science - Capsule	985	15	.010	.031	061	•073
Capsule Deorbit Maneuver	1000	-	.009	.029	.057	.085
Capsule Atmospheric Entry	1001	-	.0091	.028	.056	.083

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TABLE 7. SATURN-5 STAGE RELIABILITY

JUPITER BROBE	CUMULATIVE	STAGE
FLIGHT NO.	LAUNCHES	RELIABILITY
1 2 3 4 5 6 7 8 9	55 105 180 380 430 505 555 605 630	•935 •942 •948 •955 •956 •957 •958 •959

Assumptions For Table 7:

- 1. First Saturn-5 Launch 1965
- 2. Fifty-five (55) Saturn-5 Launches prior to launch of first Jupiter Probe. Cumulative Saturn-5 launches at time of subsequent Jupiter Probe launches shown in Table L.
- 3. Stage Reliability $(R_S) = 1 \infty L^{-\frac{1}{2}}$, according to Reference 2; where

L = Cumulative launches

6 = 0.19 for Saturn-5

4. Guidance Reliability

To Earth Orbit (R_{GO}) - 0.990

From Earth Orbit To Injection (R_{GI}) - 0.980

5. Restart Relimbility (R_R) Third Stage (S-IV B) - 0.940

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TABLE 8. SPACECRAFT RELIABILITY DATA JUPITER PROBE

engineering Subsystem	SINGLE USE RELIABILITY	FAILURE RATE *
SPACECRAFT ENGINEERING		
Guidance & Navigation *		70
Attitude Control		27
Power Supply		10
Communication**		43
Propulsion		·
Injection Guidance Maneuver	0.95	
Midcourse Guidance Maneuver	0.90	
First Approach Guidance Maneuver	0.85	
Final Approach Guidance Maneuver	0.80	
Capsule Release	0.95	·
CAPSULE ENGINEERING		
Guidance & Navigation *		47
Attitude Control		9
Power Supply		6
Communication **		- 28
Propulsion		
Planet Capture Maneuver	0.90	
Deorbit Maneuver	0,90	

^{*} Includes Computer, Programmer, Etc.

^{**} Includes Encoders, Data Storage, Etc.

⁺ Failure Rates are for Engineering Subsystems and Associate Thermal Controls.

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TABLE 9. SPACECRAFT RELIABILITY DATA JUPITER PROBE

SCIENCE SUBSYSTEM	SINGLE USE RELIABILITY	FAILURE RATE* X 10-6/HR
SPACEORAFT SCIENCE		
Spectrometers		40
Magnetometers		20
Radiation Detector		15
Meteoroid Detectors		5
Infrared Radiometer		15
Microwave Radiometer		15
Radio Noise Detector		25
Television Camera		70
CAPSULE SCIENCE		
Radiometer		20
Meteoroid Detector		5
Radiation Detector		15
Magnetometers		20
Atmospheric Entry Sensor	0.98	

^{*} Failure Rates are for Science Sensors, Associate Control Units and Thermal Control.

LOCKHEED-CALIFORNIA COMPANY PREPARED BY REPORT NO LA 17358 A DIVISION OF LOCKHEED AIRCRAFT CORPORATION CHECKED BY PROPINSION. LAUNCH TO EARTH ORBIT INTERPLANETARY INTECTION 0.9 0.8 JUNITER PROBE 0.7 TOTAL NUMBER OF SATURN-5 LAUNCHES (L) *10 MOURE 8 LAUNGE CONTOUR PORTABILITY FOR

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5.6.2 Cost

In analyzing the cost of advanced missions where subsystems are at best, not well defined, the following three-step procedure is utilized.

Step One

Analyze past program for the distribution of effort in these categories:

Engineering

Flight Hardware

GSE

Supporting R&D

Facilities

Payload Integration

Operations

In this way the ratio of Total Program Cost to Flight Hardware Cost on past programs can be determined. Tables 10 and 11 represent the results of this type of analysis on Mariner II and Mercury.

Step Two

In each mission the Flight Hardware Costs are determined using subsystem weights obtained from the Vehicle Design Analysis, Section 5.4, and subsystem parametric cost data developed. For example, for rocket engine costs are shown in Figure 10. Other cost estimating yardsticks are tabulated in the Appendix.

Step Three

Obtain the Total Program Cost as follows:

Now in the Mariner II, a past program similar in distribution of effort to the Jupiter Probe we see from page 35 that:

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5.6.2 (Co	nt'd) for JUPITER PROBE:		,
	TOTAL PROGRAM = FLIGHT HARDWARE COST	X 2.86 TUPITER PROBE	
The calcula	ation of the Jupiter Probe Costs are sho	own on pages 38 t	hrough 41 and

The calculation of the Jupiter Probe Costs are shown on pages 38 through 41 and summarized on page 42.

TABLE 10

MARINER - II

TTEM	COST	PERCENTAGE
ENG INEER ING	\$,	
Launch Vehicles		
1st Stage		
Upper Stage		
Propulsion		
Guidance & Control		
G SE '		
Spacecraft	15.0	
GSE	2.0 17.0	23.7
FLICHT HARDWARE		
Launch Vehicles - 2 at 8.5	17.0	
(Atlas - Agena)		
Spacecraft 2 at 4.0	8.0 25.0	35.0
GSE		
For LV & SC	4.0	5.6
SUPPORTING R&D	7.0	9.8
FACILITIES	4.0	5.6
PAYLOAD INTEGRATION	1.0	1.4
OPERATIONS		
Ground	2.5	
Launch & Flight	ì	
	13.5	18.9
TOTAL	71.5	100.0
•		

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TABLE 11 MERCURY

ITEM	COST - \$M	PERCENTAGE
ENGINEER ING		
LAUNCH VEHICLES		
First Stage		ŀ
Upper Stage		
Propulsion		
C&C		
GSE	11	2.1
SPACECRAFT	66	12.7
GSE	2	0.4
		15.2
FLIGHT HARDWARE		
IAUNCH VEHICLES		
Atlas 7 x \$8.5	60	11.6
Spacecraft 26 x \$3.6	94	18.2
		29.8
GSE - For Launch Vehicle and S/C		
	78	15.1
SUPPORTING R & D	75	14.5
PAYLOAD INTEGRATION	2	0.4
OPERATIONS		0.4
GROUND	(5	
LAUNCH & FLIGHT	65	12.6
	29	
	de l'ai	55.0
	\$517M	100.0%

^{* 26} vehicles; 7 launches Spacecraft Weight 4753 lbs.

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	COST METHOD		
	OGDI PERILOD		
JUPITER PROBE			
For OM-3a/S-5 the follow	wing weights are used	in costing the Fligh	t Hardware:
			State of the
TRIP TIME	997 DAYS	730 DAYS	
			
S/C Total Weight	11000 lbs	13200 lbs	
Less Main S/C Propellant	- 2830	- 3400	
Tora Canquia Dannail	03.50		
Less Capsule Propellant	- 3150	- 4450	
Net Inert	5020 lbs	5250 350	
· · · · · · · · · · · · · · · · · · ·	7000 100	5350 l bs	

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ጥጹፐው ጥፒለሹ	3	997 DAYS		730 DAYS	<u> </u>	
	•			<u>-</u>		
ITEM	S B T	\$/IB	\$, 10 ⁶	Sali	\$/IB	\$, 10 ⁶
STRUCTURE	1790	8000	14.32	2070	8000	16.55
GUIDANCE & CONTROL	835	3000	2.51	835	3000	2.51
PROPULSION	180 (T = 4000)	35.0*	41.	230 (T = 6000)	32.0*	.19
AFU	850	0009	5.10	850	0009	5.10
COMMINICATIONS	7480	2000	%	1480	2000	%
ECS	620	. 5000	3.10	620	2000	3.10
SC PAYLOAD	265	20000	7.30	265	20000	7.30
* \$/ILB OF THRUST	5020		33.43	5350		35.71

JUPITER PROBE - COST OF MAIN SPACECRAFT & CAPSULE

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COST METHOD

JUPITER PROBE - 997 DAYS

3 LAUNCHES

3 S-5 at 50 x 10^6 = \$150.0 x 10^6

3 S/C at 33.43 x 10^6 = 100.3×10^6

\$250.3 x 10⁶

TOTAL PROGRAM COST = $250.3 \times 10^6 \times \frac{100.0}{35.0}$

LESS DEV. FOR

NUCLEAR APU

= \$715 x 10⁶

 \triangle DEV. FOR N. APU = 287×10^6

\$1.002 x 10⁹

6 LAUNCHES

ADD 3 (33.43+50.0) x 10^6 x ($\frac{35.0 + 18.9}{35.0}$) =

FOR 35% FLT. HDW.

& 18.9% OPERATIONS THEREFORE

ADD 3 (83.43) \times 10⁶ \times 1.54 = \$385 \times 10⁶

9 LAUNCHES

ADD $2 \times 385 \times 10^6 = 770×10^6

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COST METHOD

JUPITER PROBE - 730 DAYS

3 LAUNCHES

3 S-5 at 50.0 x 10⁶

= \$150.0 x 10⁶

3 S/C at 35.71 \times 10⁶

 $= 107.1 \times 10^6$

\$257.1 x 10⁶.

TOTAL PROGRAM COST = $$257.1 \times 10^6 \times 100.0$

LESS DEV. FOR

NUCLEAR

= \$736.0 x 10⁶

DEV. FOR N. APU

\$287.0 x 10⁶

\$1023.0 x 10⁶

6 LAUNCHES

ADD 3 (35.71) + 50.0) $\times 10^6 \times 1.54 =$

 $3 (85.71) \times 10^6 \times 1.54 = 396×10^6

9 LAUNCHES

ADD $2 \times 396 \times 10^6$

= \$792 x 10⁶

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COST METHOD

JUPITER PROBE - COST SUMMARY

	TRIP TIME	
NO. OF LAUNCHES	997 DAYS	730 DAYS
3	\$ 1.002 x 10 ⁹	\$ 1.023 x 10 ⁹
6	1.387 x 10 ⁹ •	1.419 × 10 ⁹
9	\$ 1.772 x 10 ⁹	\$ 1.815 x 10 ⁹
1		

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5.6.3 System Performance Index

The criterion used for the evaluation of system candidates is called System Performance Index (SPI). The definition of the SPI for a single-launch program is:

System Performance Index (SPI) =
$$\frac{\sum_{i=1}^{n} (\Delta m.r.)_{i} R_{i}}{Cost}$$

where;

(Am.r.) = Incremental mission return factor of the ith mission objective

R = Probability of successfully accomplishing the i th mission objective

Cost = Total Cost of a single - launch program.

For a multiple-launch program in which reliability growth between the first and last launches is negligible, assumes a more general form: namely;

$$(SPI)_{L} = \sum_{1}^{n} (\Delta m.r.)_{1} \left[1 - (1 - R_{1})\right]^{L}$$

$$(Cost)_{L}$$

where:

L = Number of launches
(Cost)_L = Total cost of a "L" - launch program.

and where all other parameters are as defined previously.

The System Performance Indices for 3, 6 and 9 launch programs and for both 997 and 730 day trip times are plotted in Figure 11.

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E LAUNCHES	5/		47.E	DULE	6
NUMBER OF	730 MYS		NEE	NORMAL SCHE	7 HES
INDEX VS	WIL OF THE PROPERTY OF THE PRO		DE	%	S 6 OF LAUNC
REGENANCE					4 NUMBER
SYSTEM PER		:			m
SYSTER			•		N
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5.6.4 Programming Variations

In order to evaluate the system candidates within a mission, the following programming variations were considered:

Number of launches
Launch date
Trip time
Type of schedule

These items obviously have influence on the cost and energy required. Not so obvious is the influence of the type of schedule on cost. In general what is meant here is the influence of an accelerated, normal, or relaxed type of schedule on total program cost.

In order to illustrate the influence of the type of schedule on the Jupiter Probe total program cost, Figure 12 is shown. These curves were obtained by calculating
total program costs for a normal schedule and constructing the curves in the following way. For example the relaxed-schedule time is sufficiently long to allow
incorporation of design improvements between operational launches, whereas, the
accelerated-schedule time is considered the absolute minimum time assuming the
application of infinite resources. Moreover, the relaxed-schedule cost is obtained
by extrapolating the normal schedule costs along a line parallel to the constant
cost line; whereas the accelerated schedule costs were obtained by assuming that
four independent, concurrent design and development approaches were required.
Perhaps, a better way to obtain the accelerated schedule costs would be to extend
the curves for each number of launches asymptotically to the estimated minimum
time.

TAL PROSEAM COST VS SCHEDULE TELEMENT COST VS SCHEDULE TELEMENT COST VS SCHEDULE TELEMENT COST VS SCHEDULE TO STAND CONSTANT COST SCHEDULE TO S	PREPARED BY DATE	LOCKHEED CALIFORNIA COMPANY A DIVISION OF LOCKHEED AIRCRAFT CORPORATION	PAGE 46
TAL PROSEAM COST VS SCHEDULE FEGURE 12 FIGURE 13 FIG	CHECKED	т	
TAL PROCRAM COST VS SCHEDULE FIGURE 12 FIGURE 12 THIS TIME 9971 THIS TIME 9971 THIS TIME 9971 THIS TANK ASSTANT CONSTANT COST CONSTANT COST STANT COST CONSTANT COST COST CONSTANT COST C	APPROVED	<u> </u>	LE 17358
	PROGRAM COST VS SCHEDULL	7.ME 7.ME + 9 6 4	3 4 5 6 7 8 9 10 11 12 13 14

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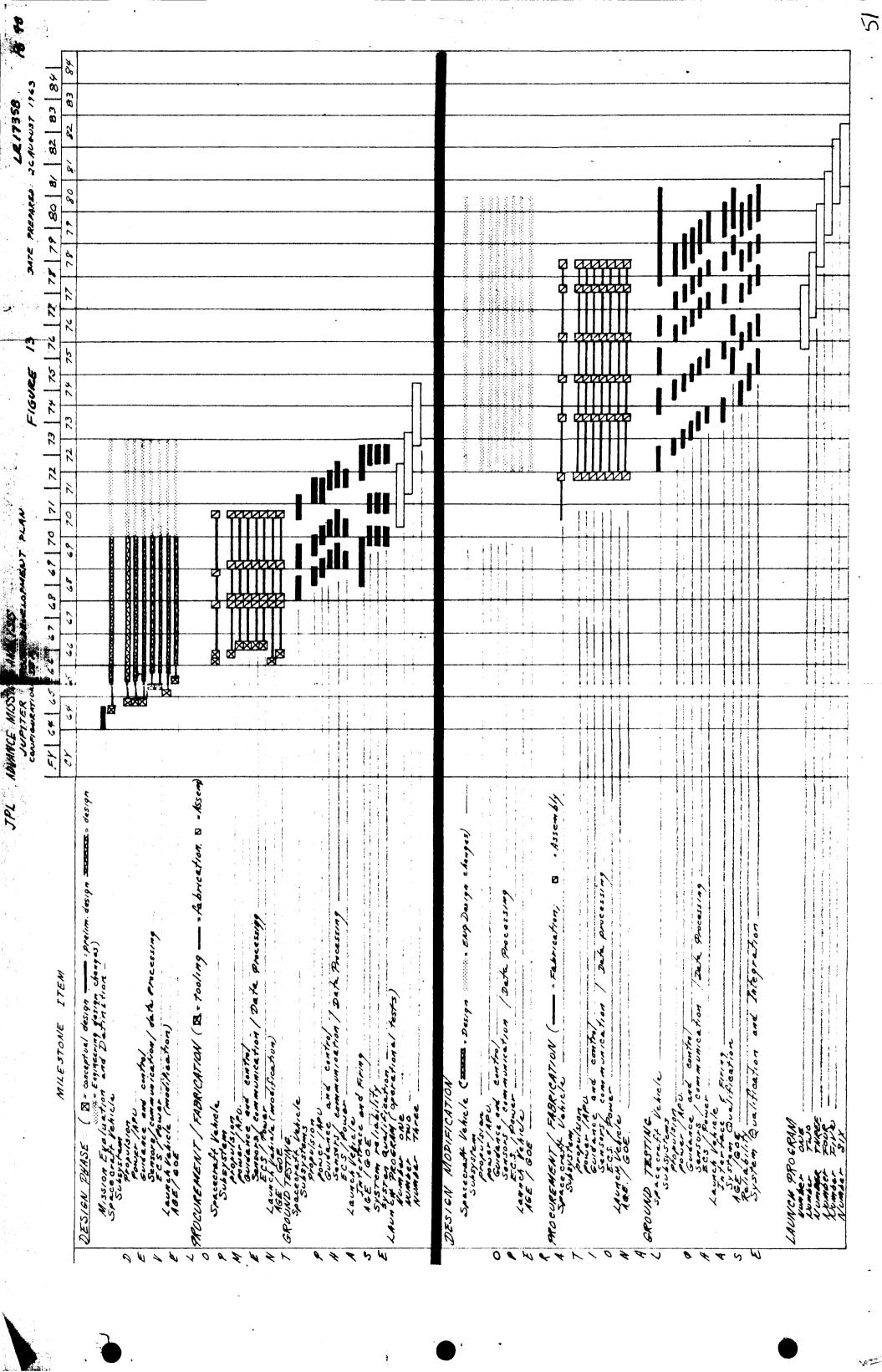
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5.6.5 Development Plan

A brief development plan for a nine launch Jupiter Probe mission is shown in Figure 13. Attention is invited to the fact that although the first three launches are shown under the Development Phase, these launches are trials with full system objectives.

The item shown as Design Modification continues after launch number three at a reduced level and represents the effort necessary to incorporate design improvements as a result of learning during operational flights.

It is quite evident that one of the key features of a multiple launch, Jupiter Probe mission is the long program and flight durations. The program could easily cover ten to fourteen years.



5.7 Mission Evaluation

The system performance index, S.P.I., described in Section 5.6.3 of this report enables the comparative evaluation of operational-mode/system-candidate combinations within one particular mission. An additional criterion is required to compare operational-mode/system-candidate combinations of one mission with those of another mission. It can be reasoned that the best operational mode/system candidate combinations from each mission can be compared if a factor of the relative value of each mission is introduced.

In this study the Mission Evaluation Criterion (M.E.C.) was used as a basis for this comparison.

The Mission Evaluation Criterion can be defined as follows:

Mission Evaluation Criterion (MEC) = (S.P.I.) Vm

where Vm, called the Relative Mission Value, is a value judgment assigned to missions on the basis of their relative contributions to national objectives within the framework of the following considerations.

- 1. Science
- 2. Engineering
- 3. Political
- 4. Manned Space Flight
- 5. Military
- 6. Economic

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5.7 Mission Evaluation

The Relative Mission Value (Vm) deals largely with the intangibles associated with the performance of missions and cannot be generated by known analytical techniques. These intangibles or imponderables may, in many instances, transcend engineering and science considerations in establishing the desirability of conducting a mission.

In this study Relative Mission Values were obtained from the results of a survey conducted at the Jet Propulsion Laboratory. A questionaire was distributed among key personnel to solicit their judgments in assigning values to the missions in the categories stated. The results of this survey, normalized to the Jupiter Probe are:

MISSION	Vm
Jupiter Probe	1.0
Manned Lunar Base	2.63
Earth Orbiting Space Station	2.40
Manned Mars Landing	3.22
Unmanned Sample Return From Venus	0.69

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6.0 RESULTS FOR OTHER MISSIONS

Information pertinent to the evaluation of other missions covered in the study is summarized in this section. Additional supporting data are presented in the appendix.

6.1 System Definition

Mission Two - Manned Lunar Base

The Manned Lunar Base evaluation was made for a postulated mission in which a temporary base would be established in the vicinity of Mare Nubium. The base consists of laboratories, observatories, living quarters and associated facilities. The base would support the exploration of natural phenomena within a 200 - 300 mile radius of the Maria and would enable earth and astronomical observations.

The mission entails a one-year presupply phase and subsequently a one-year operation phase. During the first year a total of one million pounds of cargo will be transported to the lunar surface for base construction and activation. From three to nine crew members will be required on the lunar surface to perform these functions. Crew members will be rotated every 30 to 60 days in this initial phase. During the second or operation phase, fifteen crew members will be required to man the base and conduct lunar exploration; these men will be rotated on a six-month basis. The base will be resupplied with one-half million pounds of cargo during the operation phase.

The Manned Lunar Base Mission evaluation was based on the use of a modification of Operational Mode 4, as described in Monthly Progress Report No. 3. This mode, as modified, entails the transportation of all cargo to the lunar surface by means of direct unmanned flights. The lunar landing operations of these flights are supervised, i.e. controlled, by base-assembly crew members. These personnel are transported by separate flights in which the lunar-orbit rendezvous technique is utilized. Base operation personnel are transported by yet another means; namely, direct flight to the lunar surface where a portion of the landing stage is refueled for the earth return journey.

The system candidate on which the evaluation was made for the Manned Lunar Base mission is described in Tables 12 through 16. The presupply and resupply cargo weights are summarized in Tables 12 & 13. The flight vehicles required for the

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Mission Two - Manned Lunar Base (Cont'd)

entire mission are enumerated in Table 14. Saturn 5 vehicles are used for all launches, and Apollo modules were utilized in the spacecraft whenever practicable. Descriptions of a Lunar Logistics Vehicle (LLV) and Modified Apollo Service Module, defined for this study are presented in Tables 15,16. The LLV is used in both the presupply and resupply cargo flights and the Modified Service Module is used in the transportation of base operation personnel. The latter module is equipped with throttleable engines and landing gear to permit descent to the lunar surface from orbit. The Service Module is also used to provide earth-return propulsion after being refueled on the lunar surface.

The velocity requirements for the cargo and personnel flights are presented in Table 17. These data were used in determining flight performance for which calculations are summarized in the appendix. Also shown in the appendix are:

(1) the distribution of incremental mission return factors; and (2) a functional sequence for the mission.

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TABLE 12

PRESUPPLY WEIGHT SUMMARY/MANNED LUNAR BASE

Living Quarters	100,000 lb.
Base Operation, Crew Support, & Logistics Quarters	125,000
Life Support & Environmental Control Systems (20,000) & Supplies (40,000)	60,000
Construction Equipment	80,000
Communications Systems	15,000
Power Station & Power Distribution Equipment	40,000
Observatories & Laboratories	125,000
Scientific Equipt. (110,000) & Supplies (20,000)	130,000
Lunar Surface Vehicles	110,000
Emergency Earth-Return Vehicles (60,000) & Propellants (130,000)	190,000
Miscellaneous Supplies & Equipment	25,000
TOTAL	1,000,000 lb.

TABLE 13 RESUPPLY WEIGHT SUMMARY/MANNED LUNAR BASE

Life Support & Environmental Control Supplies	40,000 1ъ.
Scientific Equipt. (50,000) & Supplies (10,000)	60,000
Lunar Surface Vehicles, Spare Parts, Fuel, Etc.	30,000
Earth-Return Propellants	345,000
Miscellaneous Supplies & Equipment	25,000
TOTAL	500,000 lb.

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TABLE 14 SUMMARY OF FLIGHT SYSTEMS/MANNED LUNAR BASE

Translunar Flight Vehicles

Presupply Cargo Carriers

Saturn 5 Vehicles
35 Required

Lunar Logistic Vehicles
35 Required

Presupply Personnel Carriers

Saturn 5 Vehicles
12 Required

Apollo Command Modules
12 Required

Apollo Service Modules

12 Required

Apollo Lunar Excursion Modules 12 Required

Base Assembly Personnel Carriers

Saturn 5 Vehicles

9 Required

Apollo Command Modules

9 Required

Apollo Service Modules

9 Required

Apollo Lunar Excursion Modules

9 Required

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TABLE 14 (Cont'd)

SUMMARY OF FLIGHT SYSTEMS/MANNED LUNAR BASE

Resupply Cargo Carriers

Saturn 5 Vehicles
18 Required

Lunar Logistics Vehicle
18 Required

Base Operation Personnel Carriers

* Saturn 5 Vehicles

10 Required

Apollo Command Modules

10 Required

Modified Apollo Service/Logistic Modules

10 Required.

^{*} First stage off-loaded 1,350,000 lb.

LOCKHEED • CALIFORNIA COMPANY A DIVISION OF LOCKHEED AIRCRAFT CORPORATION REVISIONS . REPORT NO. __ 56 PAGE NO. _ TABLE 15 SYSTEM DESCRIPTION/MANNED IL NAR BASE LUNAR LOGISTIC VEHICLE Cargo Module 32,000 lb. Cargo 28,800 lb. Structure 3,200 Propulsion Module 58,000 Propellants - LO /LH 48,800 Residual Propellants 500 Structure 5,700 LO2 Tanks (700)LH₂ Tanks (2000)Interstages & Skirts (1150)Thrust Structure (200)Heat Shield (50)Landing Gear (1600)Propulsion Inert 1,700 ☐ Engines - 2 P&W RL 10A (650) ${\rm LO}_{\scriptscriptstyle >}$ Pressurization System (300)LH₂ Pressurization System (350)Engine Controls (150)Plumbing & Accessories (250) Guidance & Navigation 1,000

300

Power Supply - H2 - 02 Fuel Cells

A DIVISION OF LOCKHEED AIRCRAFT CORPORATION REVISIONS . IR 17358 REPORT NO. ___ PAGE NO. ___ TABLE 16 SYSTEM DESCRIPTION MANNED LUNAR BASE MODIFIED APOLLO SERVICE MODULE Structure 9000 1ь. Body, Tank Support, Thrust (3200) Landing Gear (1000)Propellant Tanks (1800)Interstage SM/SIV B (3000)Environmental Control System 500 Propulsion System 43,800 Propulsion - N_2O_4/A erozine - 50 (42,000) Engines - 3 at 10.5 K (LEM) (900) Pressurization System (600) Plumbing, Cont. & Accessories (300) Attitude Control System 1,600 Guidance & Navigation 300

Power Supply, Dist. & Cont. -

H2-02 Fuel Cells

1800

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(1) TRAJECTORY DATA MANNED LINAR BASE TABLE 17-a

CARGO CARRIER

Total One-Way Trip Time (Hrs)	72
Velocity Increments - Lunar Landing (ft/sec x 10 ⁻³)	
Retro For Lunar Capture Orbit Retro For Descent To 1000 Ft. Altitude	3.200
Hover, Translate And Touchdown	1.000
Velocity Increments - Guidance Maneuvers (ft/sec x 10 ⁻³)	
Outbound	•500

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TABLE IT-P	
(1) TRAJECTORY DATA MANNED LINAR BASE	
APOLLO/LEM PERSONVEL CARRIER	
Total One-Way Trip Time (Hrs)	72
Velocity Increments - Lunar Landing, Liftoff, Etc. (ft/sec x 10 ⁻³)	
Retro For Lunar Capture Orbit (100 N.M.) Retro For Transfer To Elliptic Orbit	3.445
Retro For Descent, To 1000 Ft. Altitude Hover, Translate & Touchdown	6.555 .770
Launch To Lunar Orbit (50,000 Ft. Perilune) Plane Change, Rendezvous & Dock	074.9 014.
Reserve For Lunar Orbit Rendezvous (S.M.) Lunar Orbit Departure	.685
Velocity Increments - Guidance Maneuvers (ft/sec x 10 ⁻³)	
Outbound	.330

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MANNED LUNAR BASE TRAJECTORY DATA TABLE 17-c

MODIFIED APOLLO PERSONNEL CARRIER

Total One-Way Trip Time (Hrs)	772
Velocity Increments - Lunar Landing, Liftoff, Etc. (ft/sec x 10 ⁻³)	3.445
Retro For Lunar Capture Orbit (100 N.M.) Retro For Descent To 1000 Ft. Altitude Hover, Translate And Touchdown	3.445 6.555 .T70
Lunar Orbit (100 N.M.)	6.555 3.970
Welocity Increments - Guidance Maneuvers (ft/sec \times 10 ⁻³)	
Outbound	.330

6.1 (Cont'd)

Mission Three - Earth Orbiting Manned Space Station

This mission was evaluated on the basis of accomplishing two general objectives: namely; (1) to conduct earth orbit science and engineering experiments; and (2) to support earth orbit assembly, checkout and launch of lunar and/or interplanetary spacecraft. The station was assumed to be manned by 24 personnel, eight of whom would be required for maintaining and operating the station. The remainder of the crew would serve as experimenters, experimental subjects, or technicians in support of assembly and checkout operations. The operational phase of the mission was assumed to be one year in duration with crew rotation every sixty days. Laboratory equipment for science experiments and observations were considered as part of the space station system. Special equipment required in support of assembly, checkout and launch operations was considered as part of the spacecraft being prepared for launch and did not enter into the evaluation. Only the capability to provide life support and protective facilities for the personnel engaged in the latter activities was considered.

The operational mode for this mission entails the launching of the space station into near earth orbit and the subsequent activation, supply and crew rotation functions required during the one-year operation period. At the time of launch the station will be fully equipped with all operating and laboratory hardware. A minimum amount of consumables will also be on board at launch to enable station activation; however, food and water for crew consumption will be supplied on an as-required basis by a logistic supply vehicles. The logistic vehicles will also provide crew transportation, resupply of consumables, standard equipment for spacecraft assembly operations and spare parts for station facilities.

The constituent vehicles of the space station system are: (1) the space station; (2) a space station launch vehicle; (3) twelve ballistic logistic vehicles and; (4) launch vehicles for the logistic vehicles. A Saturn 5 is used to launch the space station, and Saturn 1B vehicles are used to launch the logistic vehicles. Descriptions of the space station and logistic vehicle are presented in Tables 18 and 19. The logistic vehicle is designed to carry a crew of twelve men in addition to a cargo payload of 10800 pounds to the space station. The reentry module is used for scheduled earth return trips as well as emergency escape. Velocity requirements for all propulsive functions of the vehicle appear in Table 20.

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TABLE 18

SYSTEM DESCRIPTION MANNED SPACE STATION

SPACE STATION		
Structure	•	131,420 lb.
Modules (3)	(50,030)	• ,
Tubes (6)	(33,990)	
Hub	(47,400)	
Electronics		3,080
Instruments & Panels	(1,150)	
Communications	(1,730)	
Guidance & Navigation	(200)	
Attitude Control System		3,400
Propellant	(2,000)	
Tanks & Plumbing	(1,140)	•
Reaction Jets	(260)	
Stabilization Control		2,500
Electrical Power System		34,060
Batteries	(8,320)	
Solar Cells	(24,000)	
Distribution & Control	(1,740)	
Environmental Control		20,910
Thermal Control	(6,400)	
CO2, H2O & Odor Control	(1,060)	
Air Sealed At Launch	(2,250)	
Air Tanks & Controls	(10,000)	
Oxygen Regeneration Equipt.	(1,200)	
Science Equipment & Spares		
Personnel Accommodations		1,320
Adapter & Nose Fairing		7,330
Propulsion System		8,500
		•

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TABLE 19

SYSTEM DESCRIPTION/MANNED SPACE STATION

BALLISTIC	LOGISTICS	VEHICLE

BALLISTIC LOGISTICS VEHICLE		•
Reentry Module		14,150 lb.
Structure		3,230 lb.
External - Shell, Stringers, Etc.	(1920)	, s
Internal - Couches, Shock Atten., Etc.	(960)	
Insulation	(350)	
Heat Shield		770
Environmental Control System		1,290
CO ₂ & Odor Removal System	(140)	
Food, Water O2, N2, Etc.	(670)	
Containers, Heat Exchangers ,Etc.	(420)	
Controls	(60)	
Power Supply		1,280
Fuel Cells	(420)	
Tanks, Heat Exchangers, Etc.	(152)	
Controls & Distribution System	(310)	
Reactants - 02, H2	(258)	
Backup Battery	(140)	
Landing System		880
Parachute	(504)	
Retro Rockets	(200)	
Controls	(176)	
Reaction Control System		1,620
Engines, Tanks, Controls, Etc.	(500)	
Propellants, Etc.	(1120)	
Communication System •		260
Navigation & Guidance	•	380
Controls & Display Instr.		140
Crew & Suits		2,460
Retro Propulsion System (Solid)		1,500
E.C.S. Back Packs		50
Snorkel & Flotation Systems		110
Misc. & Syst. Integ. Umbilicals, Etc.		180

A DIVISION OF LOCKHEED AIRCRAFT CORPORATION REPORT NO. ___ LR 17358 REVISIONS _ PAGE NO. ___ TABLE 19 (Cont'd) SYSTEM DESCRIPTION/MANNED SPACE STATION BALLISTIC LOGISTICS VEHICLE Cargo Module 10,290 lb. Structure 1,600 lb. Propulsion System 8,115 Engine (527)Propellant Tanks (536)Pressurization System (179)Controls (23)Plumbing (144) Propellants (6706)Reaction Control System 270 Engines, Tanks, Controls, Etc. (70) Propellants, Etc. (200)Environmental Cont. Syst. 180 Tanks, Heat Exch'n'g'r, Etc. (70) Coolant (110)Jettison Rocket 20 System Integration Umbilicals, Etc. 105

9,500

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EARTH ORBITITING MANNED SPACE STATION LOGISTICS SUPPLY TRAJECTORY DATA

TABLE 20

Velocity Increments - Ascent To Space Station (ft/sec x 10-3)	
Transfer From 60 N.M. Orbit To 260 N.M. Orbit Plane Change	.700
Terminal Rendezvous & Docking	.410
Velocity Increments - Descent (ft/sec x 10 ⁻³)	
Separation From Space Station	.050
Retro For Deorbit	.550

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6.1	- 1	Cont	'a'	١

Mission Four - Manned Mars Lending and Return

The Manned Mars mission is a six-man scientific expedition involving a ten-day stopover on the planet's surface. The single-vehicle mission is carried out by use of a Mars orbit rendezvous technique. That is, on arrival in Mars orbit a Mars Excursion Module (MEM) is separated from the main spacecraft. The MEM then deorbits and lands while the spacecraft continues to circle the planet. The lander uses atmospheric braking for the descent phase with terminal deceleration being provided by parachute. Four of the six-man crew are landed. After a ten-day stay the MEM ascends to orbit for rendezvous with the orbiting spacecraft. After crew transfer the spacecraft departs for earth where atmospheric entry and descent are conducted as in the Apollo program.

The vehicle system defined for this mission will be assembled and checked out in low earth orbit. Five Nova class vehicles will be used to place the required components and propellants in orbit for each flight. The spacecraft consists of:

(1) A Propulsion Module; (2) A MEM; (3) A living compartment; (4) A service Module; and (5) A separate Command Module for earth atmospheric entry.

A fast nuclear reactor provides interplanetary propulsive power; three propulsion systems, each of 150,000 pounds thrust are used for earth departure. Only one of these units is retained after departure. The MEM employs liquid chemical propulsion units which use earth-storable propellants. A more detailed description of the vehicle required for a 357 day mission is provided in Tables 21 through 23.

During the interplanetary trip the spacecraft is rotated to provide approximately 0.4 earth g's. A regenerative life support system is assumed which results in total losses of 2.0 pounds per man day. The living compartment atmospheric pressure is maintained at 10 psia and the compartment is equipped with a storm cellar of 300 cubic feet for protection from solar flares.

The velocities required for the Mars mission are shown in Table 24. Velocities are given for each of three different trip times. The results of the evaluation which are presented in section 7 of this report are for a 357 day mission. Earth orbit weights and performance summaries for 410 and 450 day missions are presented in the appendix of this report. It should be noted that a stay time at Mars of 30 days is required to complete the 450 day trip.

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e velocity requirement	nts for this mi	ssion and for	the Venus miss	ion, described
section 6.4, were o	btained by modi	fication of th	e data from Re	ference .
e procedure used to	modify the data	is outlined i	n the appendix	•
			•	
		·		•
		•		

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TABLE 21

SYSTEM DESCRIPTION/MANNED MARS LANDING

CO	mmand module - 6 man reenery		12,500 lb.
	Structure	3,000 lb.	
	Ablation Material	2,000	
,	Insulation	500	
	Water	500	
	Water Tankage & Plumbing	50	
	Navigation & Guidance Equipment	350	
	Communications, Instruments & Displays	700	
	Power Supply & Distribution	600	
	Attitude Control System	600	
	Environmental Control	800	
	Earth Landing System	1,200	
	Scientific Equipment	360	
	Mars Sample	40	
	Crew Furnishings	600	
	Crew (6)	1,200	
SE	RVICE MODULE		16,500
	Structure	1,500	
	Power Supply 6 KW Nuclear	2,200	
	Electronics	300	
	Attitude Control System - Thrusters, Etc. Attitude Control Propellant	600 1,200	
	Food	7,100	
	H ₂ O closed systems	400	
	02	300	
	N_2	600	
	Fluid Storage & Regeneration Equipment	1,100	
	Temperature & Humidity Control	1,000	•
	Contamination Control	200	

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	TABLE 21	(Cont'd)					
SYSTEM DESCRIPTION/MANNED MARS LANDING							
STORM CELLAR & LIVING QUARTERS			26,0	000 1ъ.			
H ₂ O Proton Shielding		20,000 11	b.				
Structure		4,000					
Crew Furnishings, Rec. Equi	pment,						
Sleeping Area		1,200					
Environmental Equipment		600					
Intercom. & Misc. Equip.		200					
TELESCOPING SPOKES (2)			4,0	000			
Length = 75', Dia. = 4'			•				

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TABLE 22

SYSTEM DESCRIPTION/MANNED MARS LANDING

MARS EXCURSION MODULE

Descent Stage			15,300 lb.
Structure		1,860 lb.	
Landing Gear		1,500	
Parachute System		4,000	
Drag Device - Deployed During Atmospheric Entry	5	1,020	
Heat Protection		1,000	
Environmental Control System		1,220	
Food	(120)		
Water	(300)		
ø ₂	(180)		
N ₂	(40)		
Tankage, Plumbing, Storage	(250)		
Odor, & CO ₂ Removal	(170)		
Radiators, Pumps, Etc.	(160)		
Power Supply - Fuel Cells (3K	W)	1,900	
Communications & Instrumentat	ion	800	
Scientific Equipment		2,000	
Ascent Stage			34,800
Structure - Crew Compartment		1,330	
Power Supply & Distribution		500	
Electronics		700	
Propulsion		2,300	
Engine $(T = 25K lb)$	(600)		
Tanks & Sup'ts. Structure	(780) (800)		
Plumbing & Controls	(120)		
Environmental Control, Food, Water		450	

LOCKHEED • CALIFORNIA COMPANY A DIVISION OF LOCKHEED AIRCRAFT CORPORATION REVISIONS REPORT NO. LR 17358 PAGE NO. 71 TABLE 22 (Cont'd) SYSTEM DESCRIPTION/MANNED MARS LANDING Ascent Stage (Cont'd)

Attitude Control System (Incl. 600 lb. Propellant) Mars Soil Sample (Return Trip)	1,100 lb. (40)
Propellant - N ₂ O _h /Aerozine	27,040
Crew Provisions	580
Crew (4)	800

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TABLE 23

SYSTEM DESCRIPTION /MANNED MARS LANDING

PROPULSION MODULE (357 day trip)	1,731,900) lb.
Reactor Core & Reflector (3 x 1300)	3,900 lb.	
Shield (Primary), Pressure Vessel & Plumbing (3 x 650)	1,950	
Nozzle (3 x 5000)	15,000	
Pumps & Turbines (3 x 310)	930	
Controls & Misc. (1680)	1,680	
Valves (990)	990	
Shadow Shield (3x 1350)	4,050	
Support Structure (1500)	1,500	
Propellants	1,466,540	
Propellant Tanks	229,000	
Attitude Control	6 , 360	

NOTE:

- 1. Core Power = 3000 MW.
- 2. Engine Thrust = $50 \times 3000 = 150,000 \text{ LB}$.
- 3. Operating Temperature = 5000°R
- 4. $I_{SP} = 900 LB_{T}/LB_{LH_{2}}/SEC$.
- 5. Nozzle Expansion Ratio = 100/1

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MANNED MARS LANDING & RETURN TRAJECTORY DATA TABLE 24

Earth Departure Dates First Flight Second Flight Total Trip Time (Days) EARLX 4-15-83 4-22-85		1		-
	-	OPTIMUM	LATE	
				
	-83 -85	4-29-83 5-6-85	5-29-83 6-5-85	
		410	357	
Velocity Increments - Transfer, Launch, Etc. (ft/sec x 10-3) Earth Orbit (200 N.M.) Departure Retro For Capture Orbit (100 N.M.) Retro For Deorbit Launch Into Orbit & Rendezvous Mars Orbit Departure Retro For Earth Reentry (100 N.M. Alt.)	000 t t 8	31.0 15.0 13.0 1.35	29.2 1.81 0.41 1.5.0 3.0	
Velocity Increments - Guidance Maneuvers (ft/sec x 10-3) Outbound Inbound 1.0	00	1.0	1.0	

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6.1 (Cont'd)

Mission Five - Unmanned Sample Return From Venus

For the purpose of this evaluation the Venus mission was assumed to entail only those engineering functions essential to the acquisition and return of a one-pound sample. The possibility of making scientific measurements enroute or on the planet's surface was not considered since it was assumed that information acquired from previous scientific probes was sufficient to support this more ambitious venture.

The mission evaluation was based on the use of an unmanned Venus orbit rendezvous technique. On arrival in Venus orbit, an unmanned Venus Excursion Module, (VEM), is separated from the main vehicle for descent to the planet's surface. The VEM deorbits and uses atmospheric braking for descent; terminal deceleration is provided by parachute, enabling a soft landing. After sample acquisition, the liftoff stage of the VEM provides propulsive power for launch and for rendezvous with the orbiting vehicle. The earth-return flight is terminated by direct atmospheric entry and earth-surface retrieval of the sample. A total stay-time of ten days was allowed in the vicinity of the planet because of the extremely accurate tracking requirements and complex guidance maneuvers needed to effect efficient deorbit and subsequent rendezvous of the VEM.

A brief description of the vehicle system postulated for the Venus mission appears in Tables 25 through 28. A fast nuclear reactor propulsion module is used for interplanetary transfer in both the outboard and inbound legs of the journey. Only one engine is provided in the module, requiring that the unit be throttleable for earth return. Other units comprising the vehicle system are the Venus Excursion Module and Instrumentation Unit. The earth return spacecraft is a sub-unit of the VEM. The Venus vehicle is assembled in earth orbit. Inunching the required modules into earth orbit will be accomplished by two Nova class vehicles. An earth orbit space station will be required in support of assembly and launch operations. The velocity requirements for the mission are shown in Table 29. Data are given for trip times of 460, 420 and 332 days. In order to complete the 460 day mission a stay-time of 20 days would be required in the vicinity of the planet. These velocity data were obtained in the same manner as those presented in section 6.1.3

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for the Mars mission.

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TABLE 25

SYSTEM DESCRIPTION SAMPLE RETURN FROM VENUS

en i History			
VENUS EXCURSION MODULE			183,200 lb.
Retro Stage		20,200 11	o
Structure & Insulation	1,3001b.		
Engine - 40. K	800		
Plumbing, Hydraulic & Pneumatic	100		
Navigation & Guidance	200		
Power Supply - Battery, Inverter, Wiring, Etc.	150		
Propellant - N ₂ 0 ₄ /Aerozine 50	17,650		
Landing Stage		27,200	
Structure - Device For Increasing Frontal Area(including Heat Shield)	13,600 lb.		
Structure - Landing Gear	5,400		
Parachutes	8,080		
Sampler	120		
Launch Vehicle		<i>y</i> .	
1st Stage		90,790	
Structure & Insulation	4,800lb.		
Engine (s) 200 K	2,800		
Plumbing, Hydraulic & Pneumatic System	ms 200		
Guidance & Control	200		
Power Supply - Batteries, Wiring, Etc	. 300		
Propellant - N ₂ O ₄ /A-50	82,490		
2nd Stage		35,770	
Structure & Insulation	2,500 1 b.		
Engine - 40 K	800		
Plumbing	150		
Power Supply & Distribution	150		
Guidance & Control	200		
Propellant - N204/A-50	31,970		

TABLE 25 (Cont'd)

SYSTEM DESCRIPTION/SAMPLE RETURN FROM VENUS

3rd Stage - Used For Rendezvous		7,830 1	b.
Structures & Insulation	400 lb.		
Engine (s) - 5K (Throttlable)	120		
Plumbing	50		
Power Supply - Batteries & Wiring	300		
Navigation & Guidance Equipment	1,000		
Propellant - N ₂ O _{l4} /A-50	5,960		
SPACECRAFT		1,110	
SPACECRAFT SHROUD & ADAPTER		300	

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TABLE 26

SYSTEM DESCRIPTION/SAMPLE RETURN FROM VENUS

SPACECRAFT (At Start Of Transearth Phase)			• •	1,110 lb.
Midcourse Correction Stage			160 lb.	
Structure & Plumbing	26 lb.	•		
Engine $(T = 200 lb)$	10			
Propellant - Storable	124			
Retro Stage			150	
Case & Nozzle	45			
Propellant	105			
Re-Entry Module			800	
Structure	150		•	
Sample Container & Retrieval Mechanism	50			
Power Supply - Solar Panels & Batteries	100			•
Navigation & Guidance	200			•
Communication	100			
Reaction Control Syst. (incl. 30 lb Prop.)	60			
Reentry System - Heat Shield	80			
- Parachutes & Impact Attenuation	60			

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TABLE 27

400

SYSTEM DESCRIPTION/SAMPLE RETURN FROM VENUS

INSTRUMENT UNIT Structure

3,500 lb.

Structure 1,500 lb.

Environmental Control System 400

Navigation & Guidance Equipment 800

Power Supply - Conversion Equip., 400

Etc.

Communications Equip.

TABLE 28

SYSTEM DESCRIPTION/SAMPLE RETURN FROM VENUS

PROPULSION MODULE (420 day trip)		719,250 lb.
Reactor Core & Reflector	1,620 16.	
Shield, Pressure Vessel & Plumbing	950	
Nozzle	6,300	
Pumps & Turbines	420	
Controls & Misc.	560	
Valves	430	
Shadow Shield	1,920	
Support Structure	300	
Propellants	585,000	
Propellant Tanks	118,150	
Attitude Control	3, 600	

NOTES: 1. Core Power = 4000. Megawatts

- 2. Engine Thrust = 50 x 4000 = 200,000 LB

 (Throttlable to 100,000 lb with negligible loss in I_{SP})
 - 3. Operating Temperature = 5000°R
 - 4. $I_{SP} = 900 \text{ Sec.}$
 - 5. Nozzle Expansion Ratio = 100/1

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TRAJECTORY DATA UNMANNED SAMPLE RETURN FROM VENUS	M VENUS	·		
				٦
				,
	EARLY	NEAR OPTIMUM	LATE	Т
Earth Departure Dates First Flight Second Flight	11-27-77 6-29-79	12-27-77 7-29-79	2-25-78 9-27-79	,
Third Flight	2-3-81	3-5-81	5-4-81	
Total Trip Time (Days)	09†1	1420	332	
Velocity Increments - Transfer, Launch, Etc. (ft/sec x 10-3)				1
Earth Orbit (200 N.M.) Departure Retro For Capture Orbit (100 N.M.)	20.3	19.4	18.5	····
Netro For Deorbit Launch Into Orbit & Rendezvous Venus Orbit Departure	30.0	30.0	30.0	
Retro For Earth Reentry (100 N.M. Alt.)	70.1	0.1	3.0	··
Velocity Increments - Guidance Maneuvers (ft/sec x 10-3)				.,
Outbound	0.1	0.1	1.0	
		+		

TABLE 29

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6.2 Development Plans

Brief development plans and identification of long lead time development items will now be presented for Missions Two through Five.

6.2.1 Manned Lunar Base

A brief development plan for the Manned Lunar Base mission is presented in Figure 14. The achievement of operational status by the system candidate requires the development of the following long-lead-time items.

- 1. Lunar Logistics Vehicle
- 2. Modified Apollo Service Module
- 3. Lunar Surface Roving Vehicles

4

BASE DEVELOPMENT PLAN ADVANCED LOWAR

28, AUGUST 1963 DATE PREPARED

4

FIGURE

1972 54444366663533227322 1970 1970 6361 1867 1968 8961 999 99 1961 1861 7261 1965 1965 として 1964 Refuelable 3 Han Apollo Launches (Emergency Return Volveles transportated in Lunar Logistic Volveles) Petuelable 3 Han Apollo Launches 0 MISSION EVALUATION & DEFINITION.

DESIGN:

LUMAN LOGISTICS VEHICLE STRUCTURE

Refuelle 3 Man Apollo Structure

Apollo / Lem Spacecraft

Subsystem

Apollo / Lem Spacecraft

Subsystem

Talenstage for Luman Logistics Vehicle

Talenstage for Luman Logistics Vehicle

Talenstage for Luman Logistics Vehicle

Total Structure Luman Logistics Vehicle

ACE / C.E.

Mpollo / Lem ation) ation (B = Preliminary Designs . Lunar Logistics Vahicla
Retralable 3 Han Apollo
Roto Lamon Spacecraft
Lamon Vehiole
AGE 1 BOE
Retrality
System Integration & Qualification Lunar Logistics Vehicle Launchos Launch Vehicles Laureh Sporocraft Lunar Logistics Vehicle Returnable 3 Man Molls Apollo Lam Spacecraft Laurch Vehicle SYSTEM PRE-FLIBHT CHECKOUT Lunar Logistics Vahicle Rescuedate 3 Han Apollo Apollo/Lom Spaccorast Launch Vehicle PROCUREMENT / FABRICATION PROCUREMENT / FABRICATION Ground Test Lunar L GROUND FLIGHT TEST DESIGN PHASE MILESTONE FLIGHT PROGRAM 16E / GOE 100% 184 \$20 × WCWA 02664Y1034 N 65 A DRI V542A1

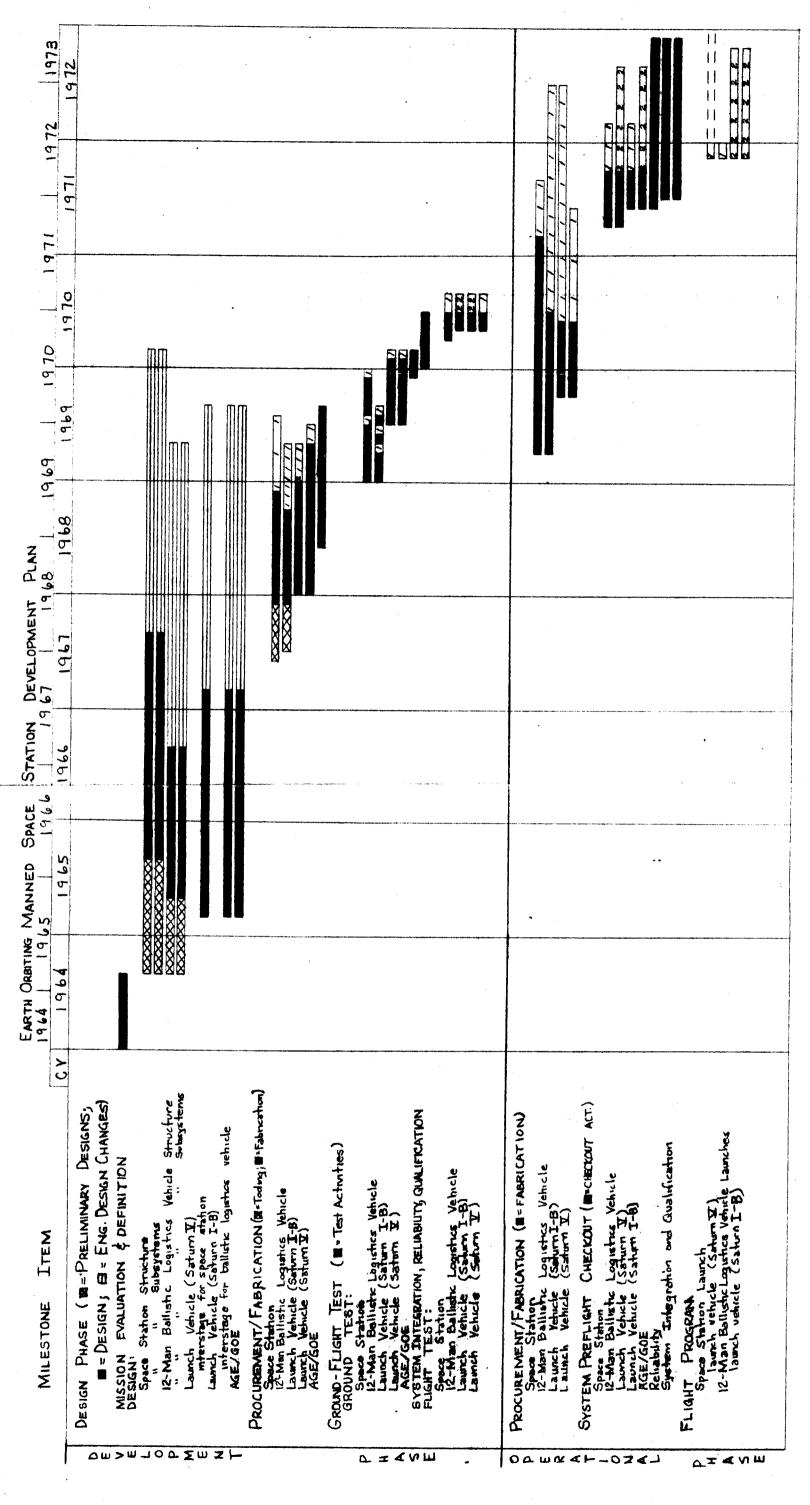
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6.2.2 Earth Orbiting Manned Space Station

Figure 15 shows a brief development and operational plan for the space station mission. The long-lead-time development items are:

- 1. Space Station
- 2. Ballistic Logistic Vehicle
 - a. Cargo Module
 - b. Reentry Module
- 3. Auxiliary Power Unit, 40 KW, for the station.



NOTE: NUMBERS INDICATE COMPLETED FABRICATION, TEST, CHECKDUT, OR LAUNCH OF DEVELOPMENT AND OPERATIONAL SPACEGRAFT.

THE LOCATION (NDICATES APPROXIMATE COMPLETION TIME AND QUANTITY.

ADVANCE
MANNED MARS

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CY	e service de la constant de la const	Z	<u>+</u>	RVICE
MILESTONE ITEM	DESIGN PHASE BEPRELMMARY DESIGNS MISSION EVALUATION AND DEFINITION DESIGN: Mission Evaluation And DEFINITION DESIGN: Muchaer Reaches/Propulsion/Shadow Shiaks Structures Mars Excursion Module Structure Service/Command Modules Structures Service/Command Modules Structure Structure Structure AGE/GOE PROCUREMENT/FARMEATIONED TOOLING BETABRICATION Nuclear Reactors/Propulsion/Shadow Shiaks Mars Excursion Modules Service/Command Modules	GROUND /FLIGHT TEST == TEST ACTIVITIES GROUND TEST: Nuclear Rectors/Propulsion/Shadow Shields Mars Exercison Module Sarvice/Command Modules Storm Cellar/Living Quarters/Spokes Lanch Vehicle KGE/GOE SYSTEM INTEGRATION, RELIABILITY, QUALIFICATION FLIGHT TEST: NATIVE Command Modules Service/Command Modules Service/Command Modules Service/Command Modules Service/Command Modules Storm Cellars/Living Quarters/Spokes Lanch Vehicle	PROCUREMENT / FABRICATION == FABRICATION Nuclear Reactors / Propulsion / Bhadow Bhields Nate Excursion Modules Service / Command Modules Service / Command Modules Service / Command Modules Launch Vehicle SYSTEM PREFLIGHT CHECKOUT == CHECKOUT Nuclear Reactors / Propulsion Shadow Shields Mars Excursion Module Service / Command Module	ANN Launch Miches Shiele ING / CHE

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6.2.3 Manned Mars Landing and Return

Figure 16 shows a brief development and operational plan for the Mars mission. The long-lead-time development items are:

- 1. Fast Nuclear Reactor Propulsion Unit
- Regenerative Life Support System
- 3. Nova Class Launch Vehicle
- Operational Earth Orbiting Space Station **†**
- Mars Excursion Module
- a. Mars Entry System
- Parachutes & Landing Gear þ,
- Propulsion System for Mars launch. ပံ
- Command Module 6.
- Service Module

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6.2.4 Unmanned Sample Return From Venus

Figure 17 shows a brief development and operational plan for the Venus mission. The long-lead-time development items are:

- 1. Fast Nuclear Reactor Propulsion Unit Throttleable
- 2. Nova Class Launch Vehicle
- 3. Operational Earth Orbiting Space Station
- 4. Venus Excursion Module
 - a. Venus Entry System
 - b. Parachutes & Landing Gear
 - c. Propulsion System for Venus Launch
- 5. Earth Return Spacecraft
- 6. Guidance & Navigation System for Unmanned Rendezvous in Venus Orbit.

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PROGRAM RETURN DEVELOPMENT LANDING AND AUVANC UNMANNED VENUS

1984 | 1985 | 1986 | 1986 | 1976 | 1978 | 1978 | 1979 | 1980 | 1981 | 1982 | 1983 | 1984 1983 7861 1861 1979 1980 000 0 <u>_00</u> 1977 1978 9251 1975 1973 1974 1972 CY 1966 1967 1968 1969 1970 1971 NoTi 0261 6961 8961 2961 9761 QUALIFIC ATION PROCUREMENT/FABRICATION ESTOCINGESFABRICATION Muclear Propulsion Stage
Very Lander
Esth Return Vehicle
Launch Vehicle
GSE/GOSS GN CHANGES systems GROUND / FLIGHT TEST #= TEST ACTIVITIES
GROUND TEST:
Nuclear Propulsion Stage
Venter Lander
Earth Return Vehicle
Launch Vehicle
GSE/GOSG
SYSTEM INTEGRATION, RELIABILITY, & QUALIFIC
FLIGHT TEST: PROCUREMENT/FABRICATION #= FABRICATION **
Nuclear Propulsion Stage
Venus Lander
Earth Return Vehicle
Launch Vehicle DESIGN PNASE = PRELIMINAR DESIGNS
MISSION EVALUATION AND DEFINITION
DESIGN:
Nuclear Propulsion 8+age Structure
... Subsystems Venus Lander Gtructure

" Subsystems
Earth Return Vehicle Structure
" Subsystems CHECKOUT Launch Vehicle interstage for launch of all GSE/GOSB SERVICING / CHECKOUT = INTEGRATION / PRE-LAUNCH CHE Nuclear Proputsion Stage Venus Lander Earth Return Vehicle Launch Vehicle Propulsion Stage Venus Lander Earth Return Vehicle Launch Vehicle ITEM Structure Launch Fuel Launches launch vehicle FLIGHT PROGRAM MILESTONE ORBITAL SI SERVICE CHECKOUT ORBITAL OAHRAH-OZAJ Q T A N W ひら とうし りり 内 舌 メ T

THE LOCATION INDICATES O FABRICATION, TEST, CHECKOUT, OR LAUNCH QUANTITY. SPACECRAFT Pro TIME OPERATIONAL COMPLETED COMPLETION DEVELOPMENT AND NUMBERS INDICATE APPROXIMATE

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			PAGE N	o. <u>• 89</u>	····
O SUMMARY OF TH	e mission evalua	MTOMO.			
					•
tention is invited	ed to Table 50,	showing a ta	abulation of th	e missions c	onsidere
d the appropriate	e data for calcu	Lating the M	ission Evaluati	on Criterion	•
		•			
•					

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SUMMARY OF THE MISSION EVALUATIONS

TABLE 30

			····					PAG
MISSION EVALUATION CRITERION	DIMI.1S, 10 ⁹	3 x t	21.20	5.03	38.80	7.98	1.08	
RELATIVE VALUE OF MISSION	DIMIT'S		1.00	2.63	2.40	3.22	69.	
SYSTEM PERFORMANCE INDEX	01 (S'.TMIG	1/2	21.20	1.91	16.18	2.48	1.56	
COST	\$, 1 0 ⁹		1.002	21.48	2.80	18.21	14.79	
PROBABLE MISSION RETURN	% OF MISSION ACHIEVEMENT, DIML'S		21.32	41.10	45.28	45.19	23.03	
MISSION			Jupiter Probe	Lunar Base	E.O. Space Station	Mars Landing & Return	Venus Sample Return	

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